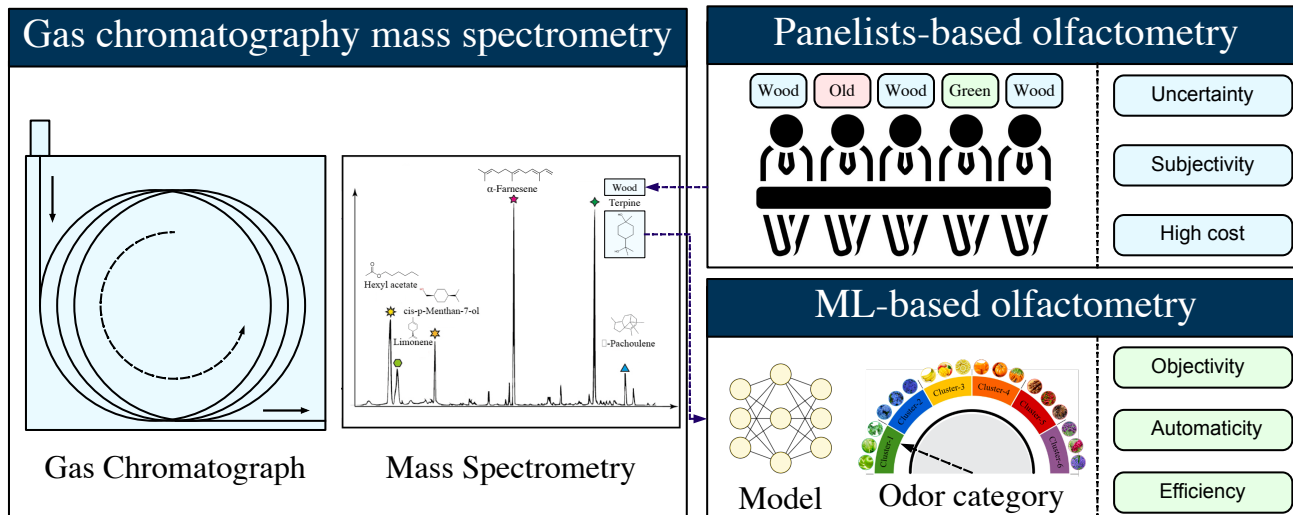


Graphical Abstract

Odorant molecular feature mining by diverse deep neural networks for prediction of odor perception categories

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5 Highlights

6 **Odorant molecular feature mining by diverse deep neural networks for prediction of odor** 7 **perception categories**

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- 9 • Different deep neural networks were used to predict categorized odor descriptors.
- 10 • End-to-end-based representation learning was performed for molecular feature extraction.
- 11 • Molecular graphs with pre-training of convolution neural networks was most accurate.

Odorant molecular feature mining by diverse deep neural networks for prediction of odor perception categories

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ABSTRACT

The prediction of structure-odor-relationship (SOR) by deep neural networks (DNN) via the structural features of odorants has attracted great attention during the past decade. Due to the limited knowledge on binding mechanism between odorant molecules and olfactory receptors, however, it is not sure what kind of structural features play the most important role in smell recognition. In this work, diverse deep neural networks, including molecular parameters neural network (MPNN), molecular graphic convolution neural network (MG-CNN), molecular graph transformer neural network (MGTNN) and atom interaction neural network (AINN), were used to extract the structure features of odorant molecules and to predict the categorized odor perception. We optimized all of the models via parameter tuning, and evaluated and compared their performance using a database containing 2849 odorants and their corresponding odor sensory category labels. The experimental results demonstrated that an MG-CNN (pre-trainedResNet) combined with a multi-label DNN classifier produced the best results, with an area under the receiver operating characteristic curve and F1 score of 0.877 ± 0.028 and 0.726 ± 0.028 , respectively. This is the first systematic study for molecular structure features extracted by different deep neural network and their predictive effect for SOR. We believe that these insights regarding the use of DNN-based odorant molecular feature extraction for odor sensory identification will be useful for introducing biologically interpretable artificial intelligence into olfactometry, and thus contribute to our understanding of the mechanisms underlying human olfaction.

1. Introduction

Identifying the interactions between odorants and sensory descriptions is important for the discovery and analysis of volatile compounds. To obtain the sensory information of odor, gas chromatography/olfactometry (GC/O) has been widely applied as a powerful odor analytic strategy in various research areas, such as agriculture, food, and environmental science [1–3]. Although GC/O can be used to attain accurate sensory and chemical characteristics of odorants, this approach is expensive and time-consuming, which can limit its application. The main expense associated with GC/O is the cost of hiring and training panelists to characterize the sensory qualities of odorants using their sense of smell. In addition, the sensory assessment of human panelists is personally dependent, which inevitably leads to subjectivity and inconsistency into the evaluation results.

Research on the response patterns of neurons in the olfactory bulbs (OB) has illuminated the mechanisms underlying biological olfaction [4–6]. However, many questions remain, such as why these molecules smell different from

one another and why we link smell feelings with certain semantic descriptors, known as odor descriptors (ODs). These questions may be answered by examining structure odor relationships (SORs), the development of which presents a difficult and interesting challenge [7–9]. During recent years, many researches have been conducted to predict odor perception of odorants using various parameters, such as electronic or physicochemical characteristics [10, 11], mass spectrometry (MS) [12, 13], and social network interactions [14]. Additionally, novel methods, such as odor-based social networks [15–17], machine learning (ML) [18–20], deep neural network (DNN) models [21–24], and semantic-based approaches [25] have been developed to calibrate models that express the relationships between odorants and ODs. These studies have demonstrated the possibility to use data-driven approaches to solve the SOR problems. In line with this trend, we have proposed a concept of ML-based GC/MS olfactometry in which the sensory evaluation of panelists is expected to be replaced by machine learning prediction models [26].

In the ML-based GC/O system, the molecular information obtained by MS analysis of the individual GC peaks is transferred into physicochemical parameters by molecular calculation software (DRAGON). By building models appropriately, the ODs of the odorants can be predicted with high accuracy from their physicochemical parameters. The

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ML-based GC/O is a concept-of-proof study and there are many problems to be solved before its practical application. For example, in terms of the sample size, only limited ODs with high frequency of occurrence are targeted in our models. In reality, it has been reported that over 500 ODs are used for odor evaluation [27]. Therefore, many ODs, especially for those rare ODs are not considered by the models. In order to solve this issue, we have recently proposed a categorization approach based on the semantic analysis of ODs, which make the model can cover the prediction of several hundreds of ODs [28]. Another remaining problem is that the model prediction is based on physicochemical parameters of odorants. The recent development of computational chemistry and ML make it possible to obtain various molecular structure information [29]. Unlike traditional methods, DNNs can directly learn latent presentations from molecular structures, such as atom types and their positions, via back-propagation [30]. Moreover, an end-to-end strategy has been proposed as an effective nonlinear modeling method for learning molecular presentation in many fields, such as quantum chemical properties prediction, and compound-protein interaction identification [31]. However, since detailed binding mechanism between the odorants and olfactory receptors is still not fully understood, which molecular features play the most important role in olfactory perception has not been cleared.

The purpose of this study is dedicated to molecular feature mining by diverse DNNs for prediction of odor perception categories. Please note that our work is not to propose some novel classification frameworks, but using multi-type of feature extractors to understand the relationship between the structure features of odorants and odor perception categories. A schematic of the data processing and modeling procedures is illustrated in Fig. 1. We used molecular structures, including 2D molecular images and atom spatial locations, to predict odor sensory categories. For mining useful information from molecular structures, some molecular structural feature extraction methods were employed and their results were compared and discussed. Specifically, we used a molecular graphic convolution neural network (MG-CNN) and molecular graph transformer neural network (MGTNN) to extract features from representations of molecular structure, such as molecular structure images and topology graphs. Moreover, we used atom interaction neural networks (AINNs) to generate features from the spatial structures of atoms. To overcome limitations related to insufficient samples, we also considered pre-trained models, such as pre-trained CNNs and MGTNNs. We compared the feasibility of SOR prediction via molecular fingerprints, molecular parameters, and molecular feature extraction based on MG-CNN, MGTNN, and AINN. We achieved the highest performance by applying molecular features extracted via a pre-trained MG-CNN combined with a multi-label learning model (area under the ROC curve: 0.877 ± 0.028 and F1 score: 0.726 ± 0.028). Thus, the proposed odor sensory category identification model is a

feasible option for developing artificial intelligence (AI)-based GC/O. Although it would be still a challenge to replace human assessors by ML models perfectly, the proposed method could provide references for assessors to increase the efficiency for odor analysis. Therefore, the limitation of odor memory would be broken through by the odor perception categories recommended by the proposed method.

2. Materials and methods

2.1. Data collection and preparation

To create an odor category prediction model, we collected an extensive dataset containing 2849 odorants. We used information from publicly available databases such as the Odor Map database [32], Flavors and Fragrances database (Sigma-Aldrich) [33], and the Good Scents database [34]. As illustrated in Fig. 1, we collected and prepared 5 types molecular descriptors, including molecular parameters, molecular fingerprints, molecular graphs, simplified molecular input line entry system (SMILES), and atom coordinates. Specifically, we used SMILES and RDKit Software (ver. 2021.03.1) [35, 36] to collect normalized molecular parameters (1826, detailed information can be found at [37]), molecular fingerprints (binary, 2048 bits), and 2D molecular graphs (RGB, 300×300 pixels). We used RDKit to obtain the 2D and 3D atom coordinates of the odorants, which we used to train the model regarding the atomic interactions between odorant structures and their odor sensory categories. In total, 256 ODs were clustered into 20 categories using a co-occurrence Bayesian embedding method. More detailed information regarding the cleaning and categorization of ODs can be found in Table S1 [28]. Data were processed and analyzed using Python (ver. 3.9.0) and R (ver. 4.1.1). Because the diverse molecular representations of odorants, we need to employ various of feature extraction technologies to obtain embeddings for model calibration.

2.2. Model calibration

The calibration and validation process for the odor category model is shown in Fig. 1. First, all samples were divided via random splitting into training and test sets with a 4:1 ratio, and the reported results are averaged over 50 repetitions. Afterward, we employed molecular parameters, molecular fingerprints, molecular graphic features, molecular graph transformers, and atomic interaction embedding to extract the molecular features of the odorants (Fig. 2). We used a DNN approach to develop a multi-label odor category learning model (the output size was 20) based on the aforementioned molecular information. The cost function $\mathcal{L}(\Theta)$ of the DNN multi-label classifier was calculated by summing the binary cross-entropy of each class, which was defined as follows:

$$\mathcal{L}(\Theta) = \frac{1}{N} \sum_{i=1}^N \sum_{j=1}^M y_{i,j} \times \log(\hat{y}_{i,j}) + (1 - y_{i,j}) \times \log(1 - \hat{y}_{i,j}) \quad (1)$$

where Θ indicates the parameter set of the model, N indicates the sample number in the training set, and M indicates the number of odor categories, set as 20 in the present study. $y_{i,j}$ and $\hat{y}_{i,j}$ are the ground truth and prediction label for category j of sample i , respectively. By minimizing the cost function based on the stochastic steepest gradient descent algorithm, parameters from the DNN could be learned and updated. For each DNN method, the number of hidden layers and nodes was selected from 1 to 8 layers and $\{16, 32, 64, 128, 256, 512, 1024, 2048\}$ nodes, respectively. Network parameters, including the dropout ratio, learning rate, and training epoch, were set as 0.1, 1×10^{-4} , and 200, respectively. The optimal models were determined according to their areas under the ROC curve (AUC) and F1 scores based on precision and recall, simultaneously. Both qualitative and quantitative data analyses were performed.

Because molecular graphs, molecular SMILES sequences, and atom coordinates are not tabular data, they cannot be used as classifier inputs directly. Therefore, diverse feature extraction methods were firstly employed to convert those unstructured data to tabular features. Specifically, pre-trained CNNs, sequence transformer, and atomic interaction embedding were utilized for molecular graphs, SMILES sequences, and atom coordinates features extraction, respectively. Detail information of above-mentioned strategies were summarized as follows.

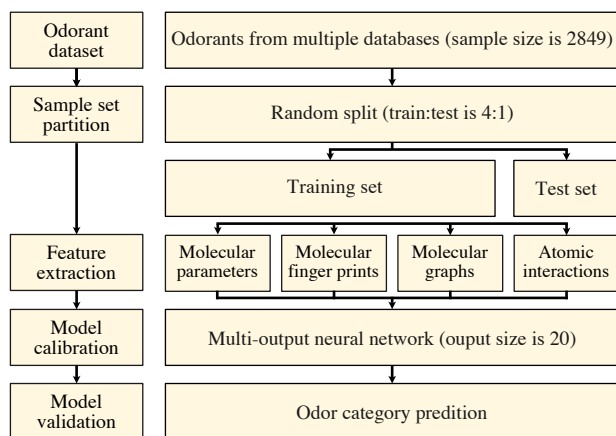


Figure 1: Data processing for calibration and validation of an odor category prediction model.

2.3. Molecular graphic feature extraction

CNNs are highly successful graphic feature extractors, and are commonly developed with high accuracy by large training datasets [38]. Given the utility of convolution kernels and DNNs, CNNs have played a critical role in image and video processing [39]. Recently, molecular graph embedding has been used to model the relationships between chemical compounds [31]. To investigate the feasibility of molecular graphic presentation for odor category prediction, we used 4 types of effective CNNs, including the VGG-16, Resnet, Densnet, and Alexnet, as feature extractors for generating embedding from molecular images in the present

study (Fig. 2a). Detailed structures for these CNNs have been previously presented [40–43]. In the present study, we used pre-trained CNN models for odor category prediction to overcome the limitation of sample size.

2.4. Molecular sequence feature extraction

As an end-to-end supervised learning algorithm, graph neural networks (GNNs) have been widely applied for sequence embedding in various fields [44]. Given that odorants can be described as molecular topology graphs using SMILES, we considered GNNs to be appropriate for molecular presentation. Broadly speaking, graph transformers are considered to be a powerful tool for handling molecular presentation through encoding via SMILES, which has been used to predict compound protein interactions, virtual screening, and molecular parameters [45].

Although the molecular graph transformer neural network (MGTNN) has strong potential for molecular modeling, deep learning models always require a large amount of labeled data for training [46]. To overcome the above problems, we used a self-supervised graph transformer (GROVER) to obtain presentation information from the odorants for odor category prediction. A briefly description of the GROVER is given in Fig. 2b. The pre-training architecture was mainly composed of two parts: i) a transformer-based neural network, and ii) a GNN for molecular structure extraction [46]. The input of the model was an odorant graph presentation $\mathcal{G} = (V, E)$, where V was the set of atoms and E was the set of bonds. Specifically, $v_i \in V$ and $e_{i,j} \in E$ were the i -th atom and bond between the i -th and j -th atom, respectively. The GNN was designed to embed extraction according to queries (Q), keys (K), and values (V) from the atoms in molecular graphs (\mathcal{G}). The message transmission process of the GNN, as well as the neighborhood aggregation between an atom (v) and its neighbors (\mathcal{N}_v) in an odorant (\mathcal{G}), were adopted to iteratively (L) update hidden states (h_v) for atom v , which can be written as:

$$\begin{aligned}
 m_v^{(l,k)} &= \text{Aggregate}^{(l)}(\{(h_v^{(l,k-1)}, h_u^{(l,k-1)}, e_{v,u}) | u \in \mathcal{N}_v\}) \\
 h_v^{(l,k)} &= \sigma(W^l m_v^{(l,k)} + b^{(l)}) \\
 h_G &= \text{Readout}(\{h_v^{(0,K_0)}, \dots, h_v^{(L,K_L)} | v \in V\})
 \end{aligned} \tag{2}$$

where $m_v^{(l,k)}$ indicates the passing message for atom v under the k -th step of the l -th iteration. Here, we suppose each iteration (l) contains K_l steps. $\text{Aggregate}^{(l)}(\cdot)$ is an aggregation function, which can be selected from the mean, max pooling, or graph attention mechanism. $\sigma(\cdot)$ is the activation function, and h_G is the graph-level representation generated by a Readout operation. The resulting matrices (Q, K, V) were fed to the transformer module, which was composed of graph multi-head attention blocks:

$$\begin{aligned}
 \text{MultiHead}(Q, K, V) &= \text{concat}(\text{head}_1, \text{head}_2, \dots, \text{head}_k)W^O \\
 \text{head}_i &= \text{Attention}(QW_i^Q, KW_i^K, VW_i^V) \\
 \text{Attention}(Q, K, V) &= \text{softmax}(QK^T / \sqrt{d})V
 \end{aligned}$$

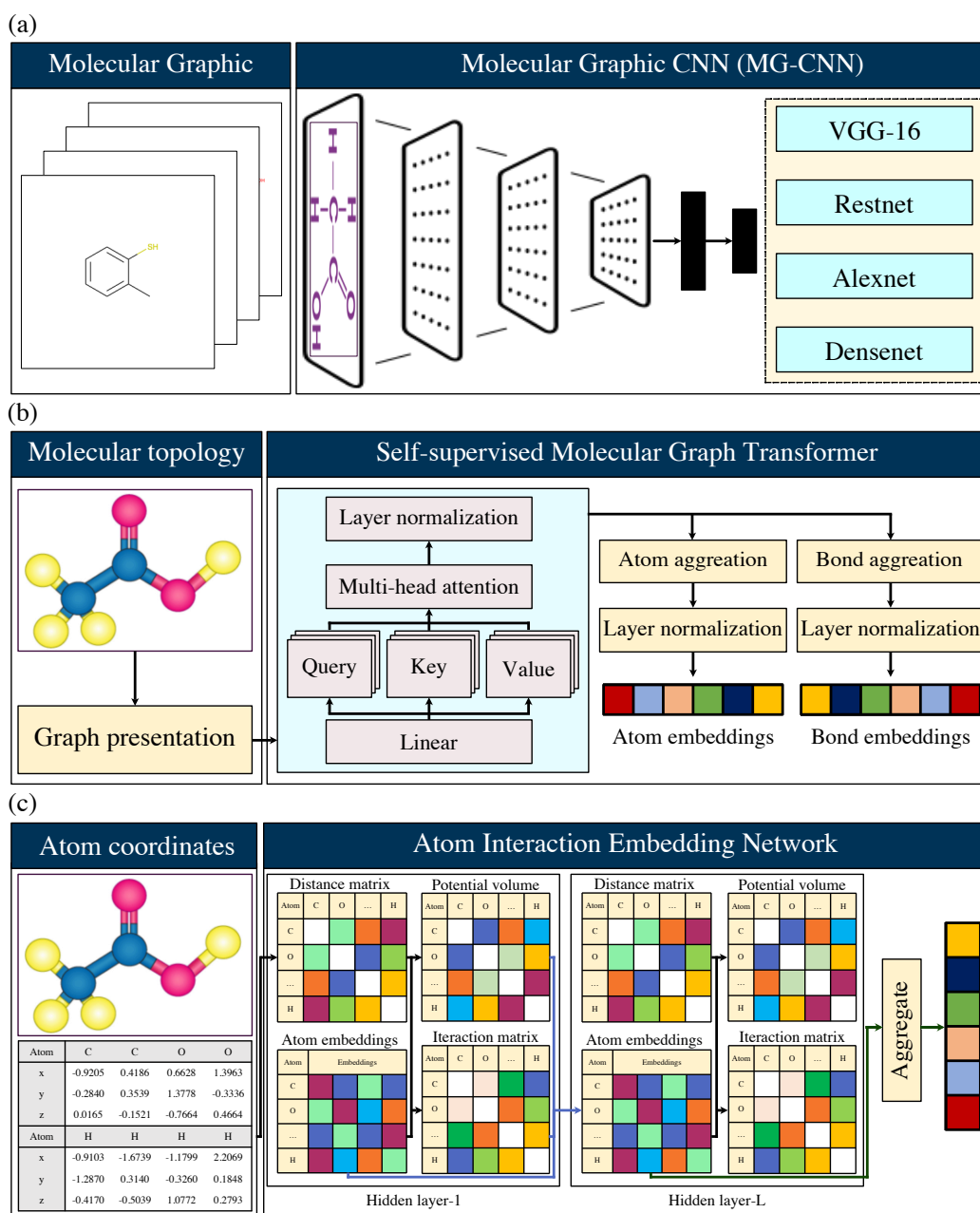


Figure 2: Overview of the design of molecular feature extractors, including (a) a molecular graphic convolution neural network (MG-CNN), (b) molecular graph transformer neural network (MGT-NN), and (c) atom interaction neural network (AINN).

(3)

246 where W_i^Q , W_i^K , W_i^V are the projection matrices of
 247 head i . d indicates the dimension of q and k .

248 The self-supervised learning tasks in the present study
 249 were assigned as contextual property prediction, and graph-
 250 level motifs, as well as molecular components, were used
 251 to predict links between both nodes and edges. In summary,
 252 we employed a pre-trained model, calibrated with 10 million
 253 molecules, as a molecular topology feature extractor in the
 254 present study. Instances of atom embedding (2048 dimen-
 255 sions) and bond embedding (2048 dimensions) generated by
 256 the above-mentioned procedure were used for odor category

257 prediction. This simple strategy has been demonstrated to be
 258 a powerful method in terms of graph expression and structure
 259 information extraction [47]. Details regarding graph
 260 transformers can be found elsewhere [48].

2.5. Atomic interaction embedding

261 Numerous studies have confirmed that atom interac-
 262 tions are crucial to odor perception [49, 50]. Consequently,
 263 molecular features generated by atomic interactions may be
 264 feasible for odor category prediction. In the present study, we
 265 modeled interactions between atoms in an odorant molecule
 266 using a DNN-based model as a molecular feature extractor.
 267 A brief description of the process for the AINN is given
 268

in Fig. 2c. Formally, given an odorant $\mathcal{O} = \{(a_i, c_i)\}_{i=1}^{N_{atom}}$, where a_i is the i -th atom type, $c_i \in \mathbb{R}^2$ or \mathbb{R}^3 is the coordinate vector of the i -th atom, and N_{atom} is the total number of atoms for the odorant. To obtain an atom embedding description for the odorant, $\mathcal{V}_{\mathcal{O}} = \{(\mathbf{v}_i, c_i)\}_{i=1}^{N_{atom}}$, where $\mathbf{v}_i \in \mathbb{R}^d$ is the embedded vector for the i -th atom. The embedding dimensionality d is a hyper-parameter that must be assigned before training, and these atom embeddings were initialized randomly and optimized via back propagation. To select the update strategy for the above-mentioned embeddings, we referred to the previous use of DNNs with common graph-structured datasets [51, 52]. Accordingly, the atom embeddings were updated as follows:

$$\begin{aligned}
 \mathbf{v}_i^{(l+1)} &= f(\mathbf{v}_i^l) + \sum_{j \in \mathcal{O} \setminus i} g(\mathbf{v}_j^{(l)}, P_{i,j}^{(l)}, \alpha_{i,j}^{(l)}) \\
 P_{i,j}^{(l)} &= f(\mathbf{v}_i^{(l)}, \mathbf{v}_j^{(l)}, dist_{i,j}) \\
 \alpha_{i,j}^{(l)} &= f(\mathbf{v}_i^{(l)}, \mathbf{v}_j^{(l)}, dist_{i,j}) \\
 dist_{i,j} &= \|c_i - c_j\|
 \end{aligned} \quad (4)$$

where $f(\cdot)$ and $g(\cdot)$ were the neural networks. $P_{i,j}^{(l)} \in \mathbb{R}$ and $\alpha_{i,j}^{(l)} \in \mathbb{R}$ indicate the potential volume and interaction factor between the i -th and j -th atoms at the l -th hidden layer, respectively. $dist_{i,j} \in \mathbb{R}$ was the Euclidean distance between the i -th and j -th atoms. Thus, the atom interaction embeddings for the odorant ($\mathbf{x}_{\mathcal{O}} \in \mathbb{R}^d$) could be calculated by:

$$\mathbf{x}_{\mathcal{O}} = \text{Aggregate}(\{\mathbf{v}_i\}_{i=1}^{N_{atom}}) \quad (5)$$

where $\text{Aggregate}(\cdot)$ was the aggregate function, which was mean pooling in the present study. As an option, we added a residual part to prevent the vanishing gradient problem in the DNN (res-AINN), which could be defined as follows:

$$\mathbf{v}_i^{(l+1)} = \text{Norm}(f(\mathbf{v}_i^l) + \sum_{j \in \mathcal{O} \setminus i} g(\mathbf{v}_j^{(l)}, P_{i,j}^{(l)}, \alpha_{i,j}^{(l)}) + \mathbf{v}_i^l) \quad (6)$$

Finally, the odorant embeddings $\mathbf{X}_{\mathcal{O}} = \{\mathbf{x}_{\mathcal{O}_i}\}_{i=1}^{N_{sample}}$ were selected as inputs for subsequent models. In this study, the hyper-parameters L , dimensions of embeddings d , learning rate η , and learning epochs were selected as 6, {32, 64, 128, 256, 512, 1024}, 0.001, and 200, respectively. We considered the feasibility of using molecular 2D and 3D coordinates, and discussed the embedding results. Detailed information regarding atom interaction embedding can be found in other publications [29].

3. Results and discussion

3.1. Data analysis

We employed five different molecular structure representations, including odorant molecular parameters (MP),

molecular fingerprints (FP), pre-trained molecular graphic embeddings, pre-trained molecular graph transformer embeddings, and atom interaction embeddings in the present study. First, we visualized the numeric vectors in low-dimensional space using Barnes-Hut t-distributed stochastic neighbor embedding (t-SNE) as an unsupervised statistical method. This method has been widely applied for high-dimensional data visualization [53]. The t-SNE presentation of the odorants based on the above-mentioned vectors is illustrated in Fig. 3 and Fig. S1. As reported in previous studies, each odorant contained multi-odor category labels [15, 16, 26, 28, 30]. Therefore, the distribution of odor categories was visualized using colors representing alpha values. Molecular graphic features extracted by Restnet (Fig. 3c) produced a better result than other molecular features because most odorants from the same odor category are clustered together. In contrast, odor cluster overlapping was observed more frequently in the t-SNE map generated from molecular fingerprints (Fig. 3a), molecular parameters (Fig. 3b), and molecular graph transformers (Fig. 3d). Molecular graphs generated from four combined types of pre-trained CNNs produced competitive results compared with other molecular descriptors (Fig. S1). This result demonstrates that odor categories are likely to be more strongly related to molecular graphs than other descriptors. Therefore, we inferred that an odor category identification model based on molecular graphic features would be superior.

3.2. Molecular graphic CNN-based feature analysis

Fig. 4 and Table S2 summarize the performance metrics of the odor category identification model based on molecular graphic feature extraction. The details of model calibration, including the optimal epochs, training loss, and elapsed time, are illustrated in Table 1 and Fig. S2. The pre-trained RestNet with DNNs (6 hidden layers) performed significantly better than the other models, with the highest AUC (0.877 ± 0.028 , $p < 0.001$) and F1 score (0.725 ± 0.0278 , $p < 0.001$) on the test sets. It was followed by the DenseNet (4 hidden layers, AUC 0.876 ± 0.029 , F1 score 0.716 ± 0.035), VGG (6 hidden layers, AUC 0.875 ± 0.028 , F1 score 0.716 ± 0.033), and AlexNet (5 hidden layers, AUC 0.873 ± 0.029 , F1 score 0.723 ± 0.033). The deep residual framework of the most successful model may have overcome the degradation problem that affects deep networks [42]. In addition, the number of hidden layers in the DNN did not play a necessary role in tuning the pre-trained CNN model. To verify the abilities of the models for transfer learning, we compared the prediction performances of the CNNs depending on whether they were pre-trained. These results are illustrated in Fig. 4. We found that the pre-trained models had significantly ($p < 0.001$) higher accuracy compared with the models with un-trained CNNs. This indicates that CNNs could learn universal image feature extractors through training with a large dataset (ImageNet). This conclusion is supported by previous research [54].

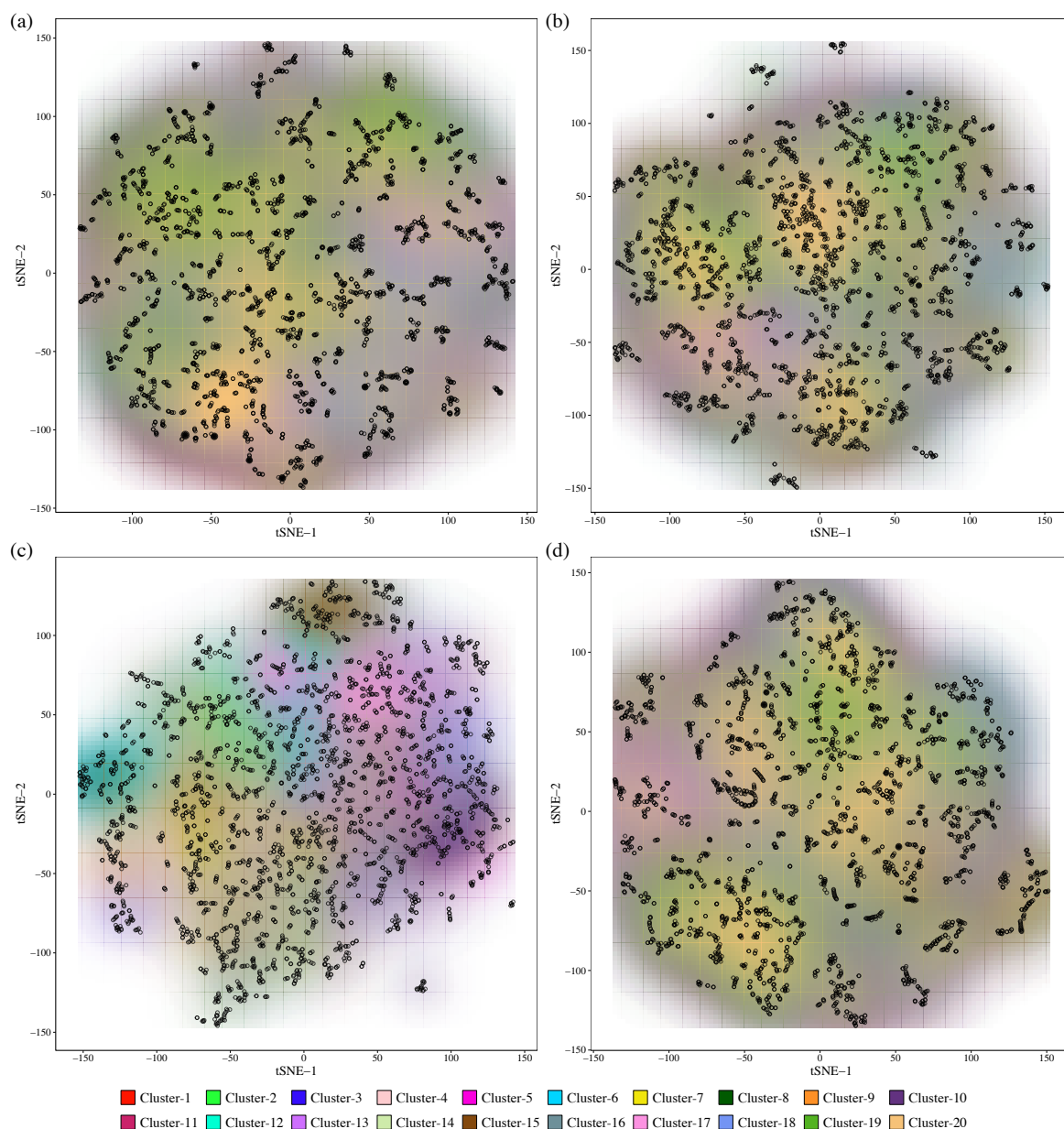


Figure 3: Odorant clustering using Barnes-Hut t-distributed stochastic neighbor embedding (t-SNE) based on (a) molecular fingerprints, (b) molecular parameters, and (c) molecular graphic features extracted via a pre-trained Resnet and (d) molecular graph transformer method based on the links between atoms and bonds. tSNE-1 and tSNE-2 were calculated using the t-SNE method. Each point indicates an odorant, colored according to its odor category labels, and the distributions of odor categories are given by the alpha values corresponding to the colors.

3.3. Molecular graph transformer based feature analysis

A summary of the identification accuracy of the MGTNN models is given in Fig. 5 and Table S3. The optimal training epoch, loss, and elapsed time for the MGTNN models are presented in Table 1 and Fig. S3. When the selected atom and bond embeddings were included with 7 hidden layers, the MGTNN model had the highest AUC (0.813 ± 0.035) and F1 score (0.696 ± 0.032) in the test set. In addition, the AUC values for the models independently trained via atom or bond embeddings were 0.812 ± 0.031 and 0.810 ± 0.030 ,

respectively. However, the data were not sufficient to conclude that considering atoms and bonds together produced a significantly more accurate result than when they were included individually ($p > 0.001$).

3.4. Atom interaction-based feature analysis

Fig. 6 and Table S4 compares odor sensory category identification according to the molecular features extracted by AINNs. The results indicated that the AINN-DNN model (2D, 512 embedded dimensions) had the highest identification performance in terms of the AUC and F1 score, which

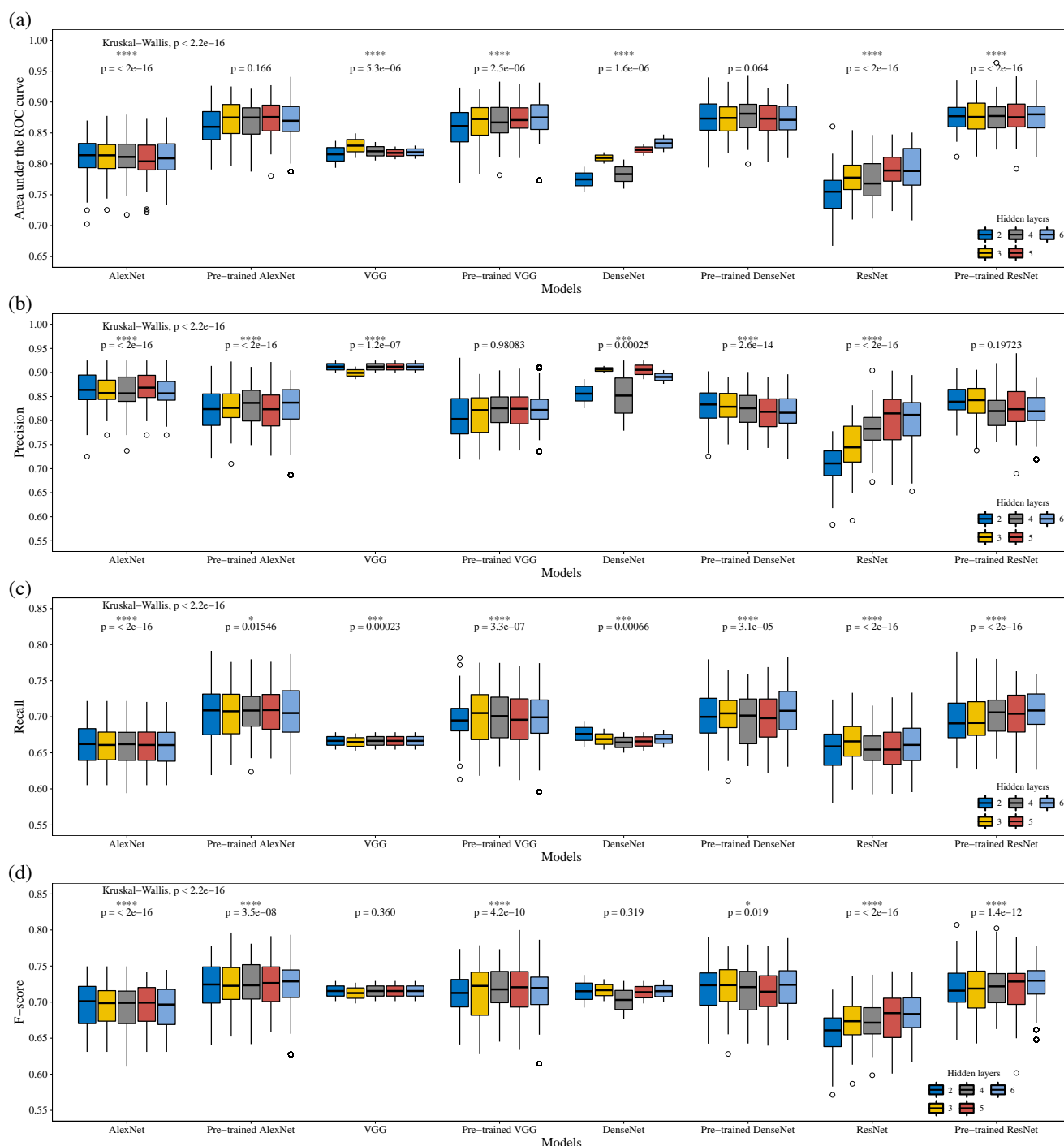


Figure 4: Identification performance of four molecular graphic convolution neural network (MG-CNN) models: AlexNet, VGG, DenseNet, and ResNet. The models were evaluated according to the average identification AUC (a), precision (b), recall (c), and F1 score (d). Results were evaluated using the nonparametric Wilcoxon signed-rank test.

383 were 0.807 ± 0.035 ($p < 0.01$) and 0.696 ± 0.023 , respectively.
 384 However, we cannot claim that the molecular 2D coordinates were better for identification than the 3D coordinates
 385 because the analyses for both had a high p-value. Further-
 386 more, the models with residual modules did not exhibit a
 387 significant increase, likely because the vanishing gradient
 388 is not the critical obstacle limiting AINN performance. In
 389

390 addition, the dimension of atom embedding vectors did not
 391 have a significant effect on the accuracy of odor category
 392 identification. The optimal training epoch, loss, and elapsed
 393 time for AINN models are listed in Table 1 and Fig. S4.
 394 We found that the modeling time for 2D coordinates was
 395 significantly smaller than that for 3D coordinates ($p < 0.001$).

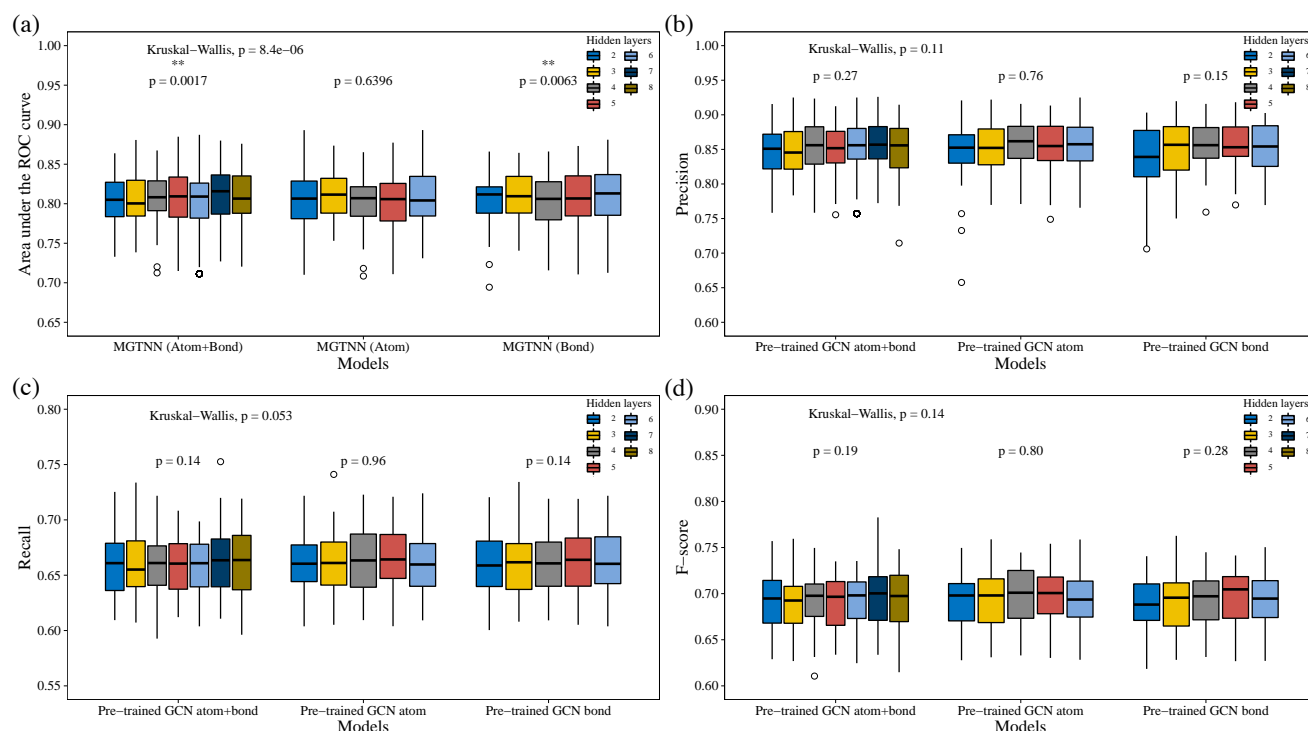


Figure 5: Determination of odor category by molecular graph transformer neural network (MGTNN) models for atom embeddings only, bond embeddings only, and combinations thereof. Models were evaluated according to the average identification AUC (a), precision (b), recall (c), and F1 score (d). Results were subjected to the nonparametric Wilcoxon signed-rank test.

396 This suggests that the presented AINN models do not need
397 spatial embedding for odor sensory identification.

398 3.5. Performance comparison

399 To identify the model with the best comprehensive
400 performance for odor category identification, we compared
401 the five types of models in terms of performance metrics, as
402 presented in Fig. 7 and Table 2. Table 1 and Fig. S5 illustrates
403 the optimal training epoch, loss, and elapsed time for the
404 above-mentioned models. The predicted accuracies for each
405 odor sensory category are summarized in Fig. S6-S10.
406 The results confirmed that the model trained using molec-
407 ular graphic features extracted via a pre-trained ResNet
408 had significantly better performance than the other models
409 (AUC 0.877 ± 0.028 , F1 score 0.726 ± 0.028 , $p < 0.0001$),
410 followed by the AINN-DNN (AUC 0.807 ± 0.035 , F1 score
411 0.696 ± 0.030), MPs (AUC 0.806 ± 0.033 , F1 score 0.689 ± 0.031),
412 MGTNN (AUC 0.804 ± 0.028 , F1 score 0.692 ± 0.029), and
413 FPs (AUC 0.796 ± 0.036 , F1 score 0.688 ± 0.033). This rank-
414 ing could likely be explained by the high correlation between
415 the olfactory sensory information and the molecular graphic
416 features of the odorants compared with the other molecular
417 descriptors. We found that the AINN-DNN model had the
418 highest precision (0.861 ± 0.038 , $p < 0.0001$). We confirmed
419 that although more epochs were needed to train the
420 ResNet models, the training time was shorter than that for
421 the AINN-DNN and MGTNN models. The fast convergence
422 speed could contribute to the transfer-learning mechanism.
423 Although the number of parameters was abundant for the

424 ResNet model, we did not train these parameters, but instead
425 used those from the pre-trained models. The pre-trained
426 models could overcome the limitation of insufficient samples
427 for training DNN models. A similar conclusion was found
428 previously [55]. In summary, we suggest that an end-to-
429 end DNN with molecular graphic features extracted via a
430 pre-trained ResNet is an optimal model for predicting the
431 sensory categories of odorants.

432 3.6. Discussion

433 The accurate and effective prediction of odor sensory
434 categories is vital for developing machine-learning-based
435 GC/O. To develop an olfaction-based sensory system, we
436 need not only bio-sensors to encode odorants (odor receptor
437 imitation), but also a brain-like odor signal decoding algo-
438 rithm. Although many studies have examined SORs, most
439 have focused on predicting ODs [15, 16, 18, 21, 31]. Even
440 though most ODs can be predicted, infrequent ODs were
441 difficult to be identified. For example, Snitz proposed a
442 mostly perfect result in predicting 64 smell percepts with
443 100 % precision and 102 smells with 90.35 %, but infre-
444 quent smells, such as almond, apricot and chocolate, had
445 been found to have poor prediction performance [16]. This
446 could be explained by the extreme imbalance in the data
447 distribution, as well as the insufficient number of training
448 samples. Unlike the above-mentioned studies, we want to
449 find useful odorant structure features for odor sensory cat-
450 egories identification.

Odorant molecular feature mining by DNNs for odor perception categories prediction

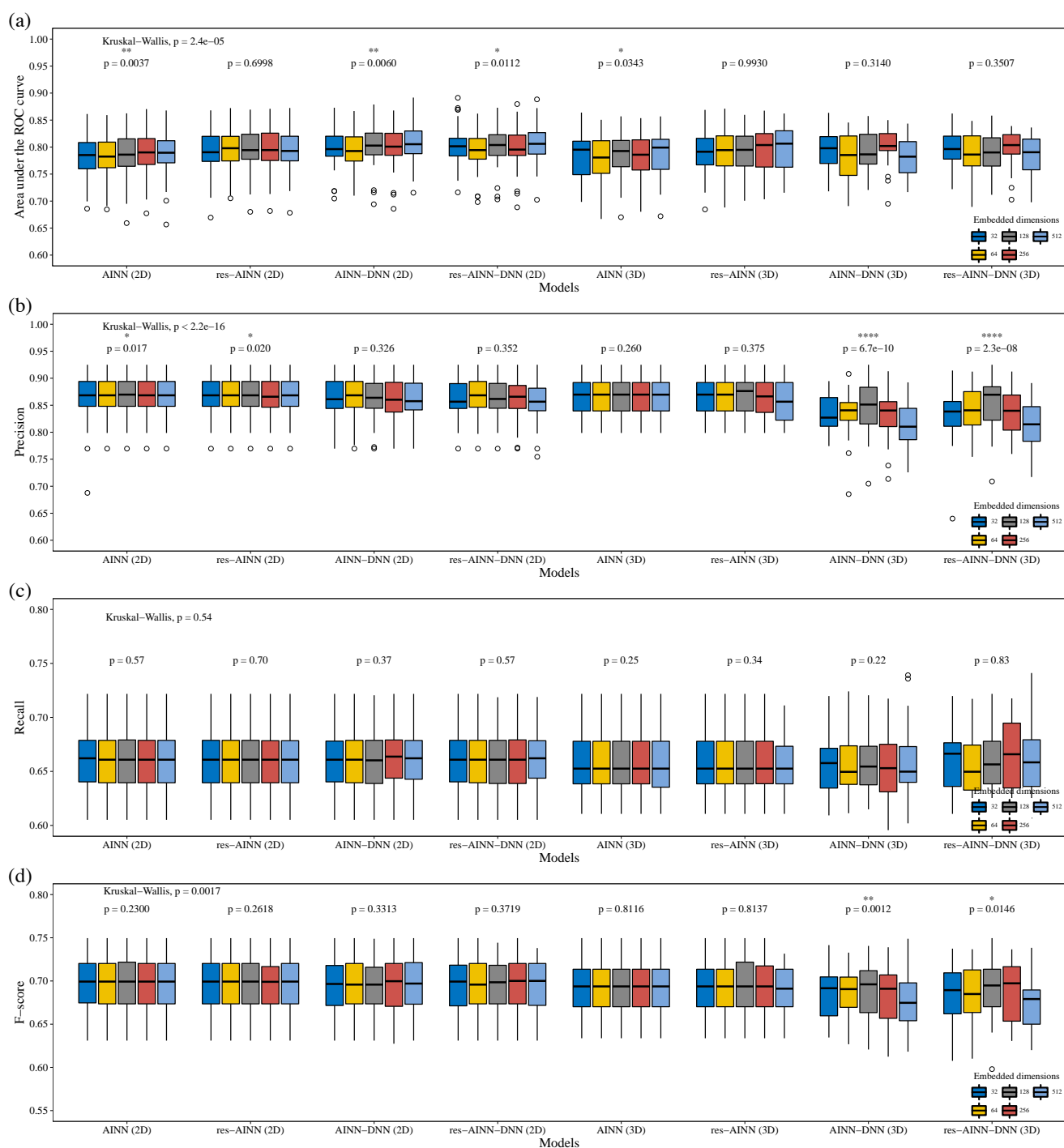


Figure 6: Results for odor category determined by atom interaction neural network (AINN) models. The models were evaluated according to the average identification area under the curve (AUC) (a), precision (b), recall (c), and F1 score (d). The data were subjected to a nonparametric Wilcoxon signed-rank test.

Table 1
Modeling and training parameters for DNN models calibration.

Model name	Input dimension	Hidden layers	Training epoch	Loss	Elapsed time (s)
FP-based	2048	6	83±42.3	0.00891±0.000942	32.5±16.6
MP-based	1000	6	91.8±46.1	0.00975±0.000528	36±18
MG-CNN-based	512	6	128±42.6	0.00672±0.000803	51.7±17.3
MGT-NN-based	4096	7	105±49.9	0.0100±0.000469	74.2±42.3
AINN-based	512	6	59±25.2	0.0107±0.000622	117±53.4

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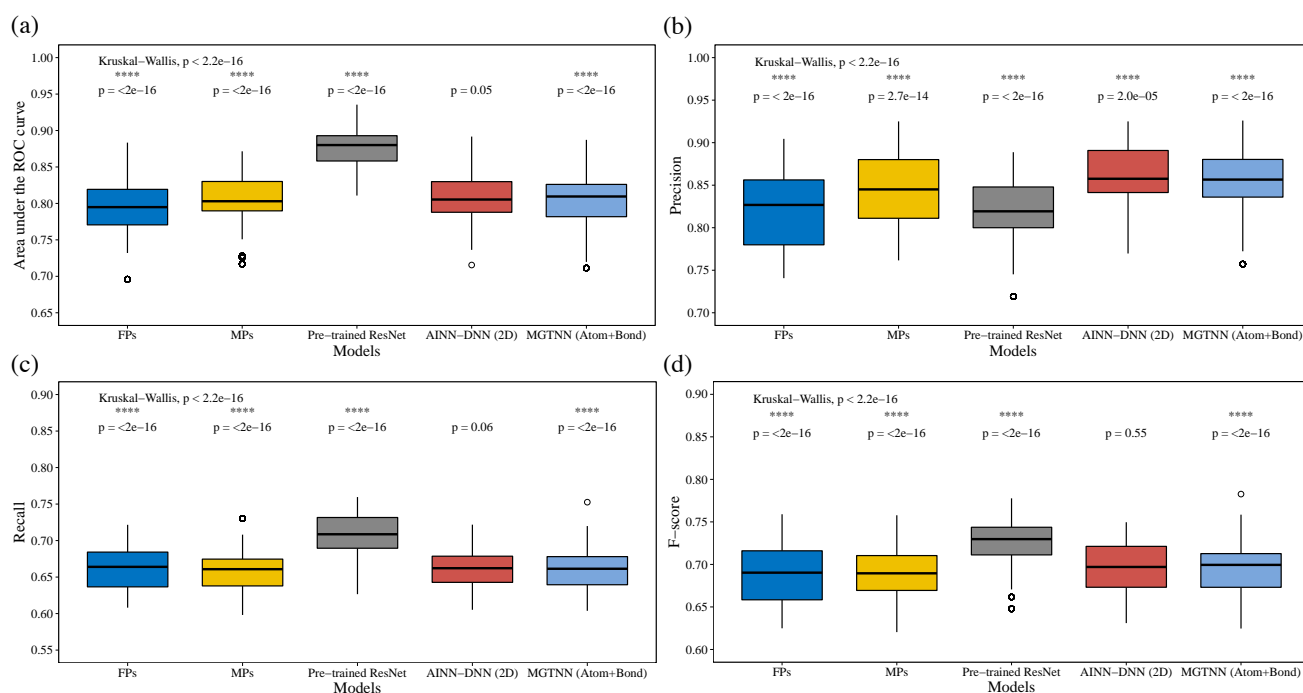


Figure 7: Identification accuracies of DNN models using molecular features extracted via FP-, MP-, MG-CNN-, MGTNN-, and AINN-based DNN models. The data were evaluated using the nonparametric Wilcoxon signed-rank test.

Table 2

Odor sensory category identification accuracy comparison of DNN models using multi-type of odorant structure features.

Model name	AUC-ROC	Precision	Recall	F1 score
FP-based	0.796±0.036	0.82±0.046	0.662±0.029	0.688±0.033
MP-based	0.806±0.033	0.843±0.039	0.658±0.028	0.689±0.031
MG-CNN-based	0.877±0.028	0.822±0.037	0.71±0.028	0.726±0.028
MGT-NN-based	0.804±0.036	0.855±0.036	0.659±0.025	0.692±0.029
AINN-based	0.807±0.035	0.861±0.038	0.662±0.027	0.696±0.030

451 Here, we focused on establishing relationships between
 452 molecular features and odor sensory categories via an end-
 453 to-end learning strategy, which is expected to play a decoding
 454 role in bio-olfaction. The MPs and FPs in the present
 455 study had poor performance, indicating that focusing solely
 456 on physiology-chemical parameters could result in the loss
 457 of some critical information related to olfaction. In contrast
 458 to relying on tabular features, molecular graph CNNs-based
 459 features would be more appropriate for learning useful odor
 460 sensory expression. We also considered a transfer learning
 461 strategy for dealing with the problem of insufficient training
 462 samples. Our results confirm that pre-trained CNNs,
 463 combined with a ‘vanilla’ DNN, can effectively establish
 464 relationships between molecular features and odor sensory
 465 categories. Furthermore, our data suggest that molecular
 466 graphic features are optimal for describing odorant protein
 467 interactions according to human olfaction. Existing GC/O
 468 methods have focused on just 8 ODs in one olfaction sensory
 469 evaluation task, as limited by the odor memory of the
 470 assessors [56–58]. Odor analysis precision is also limited by
 471 their odor memory. Therefore, the proposed model can apply

a reliable references for human panlists to reduce training
 472 cost. 473

This study has several limitations. First, more attention
 474 should be focused on atom interaction-based embeddings,
 475 although the AINN in the present study had poor performance.
 476 Biological studies have indicated that atom interactions play
 477 a critical role in mammal olfaction [59–61]. The poor accuracy
 478 of the AINN was likely caused by insufficient odorants and an
 479 inappropriate modeling approach. Moreover, we did not consider
 480 the electronic interactions between atoms, which may be suitable
 481 for olfaction sensory encoding. Self-supervised strategies
 482 combined with proper modeling techniques and trained with
 483 abundant molecules merit further investigation. Furthermore,
 484 synergism, odor neutralization and the predictable of a fragrance
 485 mixture has still not been quantified [62–64]. In present study,
 486 we focus on single odor molecule smell perception prediction,
 487 which is not appropriate for modeling odor synergism and
 488 neutralization. For fragrance mixture prediction, mass spectral
 489 would be feasible for model calibration. In the future,
 490 we plan to attempt to improve our framework for molecular
 491 492

493 structure feature extraction using other algorithms, and to
 494 try to explore the feasibility of metric modeling using Rie-
 495 mannian manifolds, such as the Grassmann or symmetric
 496 positive definite manifold [65, 66]. We expect that it will
 497 be difficult to find a reasonable algorithm when performing
 498 metric learning in Riemannian space. However, this is an
 499 interesting problem for future investigation. In addition, data
 500 fusion would also be an effective strategy for increasing the
 501 accuracy of odor category identification models.

502 4. Conclusions

503 The SOR by DNNs via the structure features of odorants
 504 has attracted great attention during the past decade. Due
 505 to the limited knowledge on binding mechanism between
 506 odorant molecules and olfactory receptors, however, it is
 507 not sure what kind of structural features play the most
 508 important role in smell recognition. Here, we utilized a
 509 DNN-based multi-label classifier for odor sensory category
 510 identification using various molecular features. Specifically,
 511 we examined the possibility of predicting odor categories
 512 based on molecular parameters, fingerprints, and graphics,
 513 as well as graph attention network embedding and atom
 514 interactions. Our results indicated that molecular 2D graphic
 515 data were strongly related to sensory information about
 516 olfaction. Extensive experiments confirmed that a ‘vanilla’
 517 DNN with molecular graphic features, extracted via ResNet,
 518 was optimal for odor perception category identification. We
 519 anticipate that transfer learning is a viable and powerful
 520 technique for modeling the relationships between molecular
 521 structures and odor perception categories. Our proposed
 522 approach could be applied in the development of AI-based
 523 odor sensors. We believe that this study is among the first to
 524 examine the importance of molecular graphic features when
 525 establishing relational models between molecular structures
 526 and odor sensory categories. Our approach may not only
 527 serve as a realistic solution for introducing AI into olfactom-
 528 etry, but may also offer a novel perspective for investigating
 529 the mechanisms of human olfaction.

530 Declaration of competing interest

531 The authors declare that they have no known competing
 532 financial interests or personal relationships that could have
 533 appeared to influence the work reported in this paper.

534 CRedit authorship contribution statement

535 **Liang Shang:** Conceptualization, Methodology, Exper-
 536 iment, Writing. **Chuanjun Liu:** Conceptualization, Method,
 537 Supervision, Reviewing. **Fengzhen Tang:** Supervision, Re-
 538 viewing. **Bin Chen:** Supervision, Reviewing. **Lianqing**
 539 **Liu:** Reviewing. **Kenshi Hayashi:** Reviewing.

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Appendix A. Supplementary data 546

Supplementary data associated with this article can be 547
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